

ABSTRACT OF THE DISCLOSURE

A hand-operated sanitary grasping device for grasping an object such as animal feces includes a control assembly, and extension structure, a support structure, which includes a pair of bag clips, a linkage assembly, a pair of scooped-shaped opposed jaws, and a pair springs. A plastic bag is placed over the jaws and attached to the bag clips on the support structure. The control assembly operates the jaws via the linkage assembly and has a latch to lock the jaws open before installing the inverted bag. The bag and jaws are placed around the object and the latch opened, allowing the jaws to grasp the object within the bag. The bag is then detached from the clips, allowing the bag to be pulled down over the jaws. The jaws may then be opened for removal of the bagged object.